JRCS016 - Non-Isolated DC-DC Buck and Boost Power Modules

$18V_{dc}$-$85V_{dc}$ input $18.5V_{dc}$ to $60V_{dc}$ output: 400W Max. Output

Description

The JRCS016 is a versatile non-isolated module capable of delivering output voltages that can be below, equal to or above the input voltage (buck and boost functionality). Over an input voltage range of 18 to 85V, these modules can provide an output voltage that can be set between 18.5V and 60V and output power up to 400W. A variable output current limit that automatically limits the output current depending on the desired output voltage safely limits the output power that can be delivered by the module. Threaded-through holes are provided to allow easy mounting or addition of a heatsink for high temperature applications. Other features include remote On/Off, adjustable output voltage, over current, and over temperature protection. The modules also have a digital (PMBus™) interface with a rich set of supported commands.

Applications

- Transportation applications
- Industrial applications
- Telecommunications equipment

Features

- Compliant to RoHS Directive 2011/65/EU and amended Directive (EU) 2015/863
- Compliant to REACH Directive (EC) No 1907/2006
- Compliant to IPC-9592 (September 2008), Category 2, Class II
- Wide variable input voltage range (18-85V_{dc})
- Programmable output voltage range (18.5-60V_{dc})
- Remote sense
- Positive logic remote On/Off
- Output over current protection (non-latching)
- Over temperature protection
- Monotonic startup under pre-bias conditions
- Forced droop load sharing (only - P version)
- Industry standard half-brick size 57.7 x 60.7 x 12.95 mm (2.27 in. x 2.39 in. x 0.51 in.)
- Wide operating temperature range (-40°C to 85°C)
- Digital (PMBus) Interface
- ANSI/UL# 62368-1 and CAN/CSA† C22.2 No. 62368-1 Recognized, DIN VDE‡ 0868-1/A11:2017 (EN62368- 1:2014/A11:2017
- ISO** 9001 and ISO 14001 certified manufacturing facilities

Footnotes

* UL is a registered trademark of Underwriters Laboratories, Inc.

† CSA is a registered trademark of Canadian Standards Association.

‡ VDE is a trademark of Verband Deutscher Elektrotechniker e.V.

** ISO is a registered trademark of the International Organization of Standards

Absolute Maximum Ratings

Stresses in excess of the absolute maximum ratings can cause permanent damage to the device. These are absolute stress ratings only, functional operation of the device is not implied at these or any other conditions in excess of those given in the operations sections of the data sheet. Exposure to absolute maximum ratings for extended periods can adversely affect the device reliability.

Parameter	Device	Symbol	Min	Max	Unit
Input Voltage					
Continuous	All	V_{IN}	-0.3	85	V_{dc}
Transient, for up to 100ms	All		-0.3	100	V_{dc}
Operating Ambient Temperature (see Thermal Considerations section)	All	T_A	-40	85	°C
Storage Temperature	All	T_{stg}	-55	125	°C

Electrical Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions.

Parameter	Device	Symbol	Min	Typ	Max	Unit
Operating Input Voltage	All	V_{IN}	18	—	85	V_{dc}
Maximum Input Current (V_{IN}= $V_{IN,\ min}$ to $V_{IN,\ max}$, I_O=$I_{O,\ max}$)	All	$I_{IN,max}$			26.0	A_{dc}
Input No Load Current	$V_{O,set}$ = 18.5V_{dc}	$I_{IN,No\ load}$		70		mA
(V_{IN} = $V_{IN,\ nom}$, I_o = 0, module enabled)	$V_{O,set}$ = 60 V_{dc}	$I_{IN,No\ load}$		70		mA
Input Stand-by Current (V_{IN} = $V_{IN,\ nom}$, module disabled)	All	$I_{IN,stand-by}$		27		mA
Inrush Transient	All	I^2t			0.5	A^2s
Input Reflected Ripple Current, peak-to-peak (5Hz to 20MHz, 1µH source impedance; $V_{IN,min}$ to $V_{IN,\ max}$, I_O= I_{Omax} ; See Test configuration section)	All				700	mA_{p-p}
Input Ripple Rejection (120Hz)	All		10			dB
Output Voltage Set-point (V_{IN}=$V_{IN,\ min}$, I_O=$I_{O,\ max}$, T_A=25°C)	All	$V_{O,\ set}$	-1.5	—	+1.5	%$V_{O,\ set}$
Output Voltage (Overall operating input voltage, resistive load, and temperature conditions until end of life)	All	$V_{O,\ set}$	-3	—	+3	% $V_{O,\ set}$
Output Voltage Adjustment Range		V_O	18.5		60	V_{dc}
Output Regulation						
Line (V_{IN}=$V_{IN,\ min}$ to $V_{IN,\ max}$)	All		—		1	% $V_{O,\ set}$
Load (I_O=$I_{O,\ min}$ to $I_{O,\ max}$)	All		—		0.4	% $V_{O,\ set}$
Temperature (T_{ref}=$T_{A,\ min}$ to $T_{A,\ max}$)	All		—		1	% $V_{O,\ set}$
Output Ripple and Noise on nominal output (V_{IN}=$V_{IN,\ nom}$ and I_O=$I_{O,\ min}$ to $I_{O,\ max}$ C_{out} = 340µF Polymer aluminum)						
RMS (5Hz to 20MHz bandwidth)	All		—		1	% $V_{O,\ set}$
Peak-to-Peak (5Hz to 20MHz bandwidth)	All		—		2	% $V_{O,\ set}$

Electrical Specifications (continued)

Parameter	Device	Symbol	Min	Typ	Max	Unit
External Capacitance						
ESR ≥ 1 mΩ (with minimum of 30µF of ceramic capacitors)	All	$C_{O, max}$	330	—	3000	µF
ESR ≥ 10 mΩ ((with minimum of 30µF of ceramic capacitors)	All	$C_{O, max}$	330	—	3000	µF
Output Current (V_o=18.5V)	All	I_o	0		16.7A	A_{dc}
(V_o=24V)	All	I_o	0		16.7A	A_{dc}
(V_o=48V)	All	I_o	0		8.33A	A_{dc}
(V_o=60V)	All	I_o	0		6.67A	A_{dc}
Output Current Limit Inception (Hiccup Mode) (V_O= 90% of $V_{O, set}$)	All	$I_{O, lim}$	—	110	—	% I_o
Output Short-Circuit Current (V_O≤250mV) (Hiccup Mode)	All	$I_{O, s/c}$	—	2.0	—	A_{rms}
Efficiency, V_{IN}= 74V, T_A=25°C, I_O=$I_{O, max}$, V_O= $V_{O,set}$ $V_{O, set}$ = 52V_{dc}	All	η	95			%
Switching Frequency	All	f_{sw}	—	220	—	kHz

General Specifications

Parameter	Min	Typ	Max	Unit
Calculated MTBF (I_O=I_O, max, TA=25°C)		19,173,816		Hours
Weight	—	112 (3.95)	—	g (oz.)

Feature Specifications

Unless otherwise indicated, specifications apply over all operating input voltage, resistive load, and temperature conditions. See Feature Descriptions for additional information.

Parameter	Device	Symbol	Min	Typ	Max	Unit
On/Off Signal interface (On/Off is open collector/drain logic input; Signal referenced to GND - See feature description section)						
Input High Voltage (Module ON)	All	V_{IH}	2	—	3.3	V
Input High Current	All	I_{IH}	—	—	100	µA
Input Low Voltage (Module OFF)	All	V_{IL}	-0.2	—	0.8	V
Input Low Current	All	I_{IL}	—	—	500	µA
Turn-On Delay and Rise Times (I_O=$I_{O, max}$, V_{IN} = $V_{IN, nom}$, T_A = 25 °C,)						
Case 1: On/Off input is set to Logic Low (Module ON) and then input power is applied (delay from instant at which V_{IN} =$V_{IN, min}$ until V_o=10% of $V_{o,set}$)	All	T_{delay}	—	90	—	msec
Case 2: Input power is applied for at least one second and then the On/Off input is set to logic Low (delay from instant at which $V_{on/Off}$=0.3V until Vo=10% of $V_{o, set}$)	All	T_{delay}	—	50	—	msec
Output voltage Rise slew rate	All	dv/dt_{rise}	—	0.333	0.4	V/msec

Feature Specifications (continued)

Parameter	Device	Symbol	Min	Typ	Max	Unit
Load Sharing Current Balance (difference in output current across all modules compared to defined output current.) (-P version only) Note: 1) Results are based on 3 units in parallel, and | V_{out}-V_{in} | >6V. If the difference between Vin and V_{out} is close, paralleled performance will decreases. 2) Current sharing accuracy depends on test setup, such as test board layout, connection wires, etc... besides module self. 3) Vout_max need to be limited to 58V if the units work in paralleling. 4) For 48V output, need limit to max 80% of full load. 5) For 54V output, need limit to max 75% of full load. 6) The difference between input and output voltage need be over 6V to get better paralleled performance.	20V_{out} 28V_{out} 36V_{out} 48V_{out}	I_{diff}	— — — —	— — — —	3 2 2 2.5	A_{dc} A_{dc} A_{dc} A_{dc}
Output voltage overshoot – Startup I_O= $I_{O, max}$; V_{IN} = 18 to 85V_{dc}, T_A = 25°C				—	5	% $V_{O, set}$
Over Temperature Protection (See Thermal Considerations section)	All	T_{ref}	—	120	—	°C
Input Undervoltage Lockout						
Turn-on Threshold	All				18	V
Turn-off Threshold	All		15			V
PGOOD (Power Good) Signal Interface Open Drain, V_{supply} ≤ 5V_{DC}						
Overvoltage threshold for PGOOD	All			112.5		%$V_{O, set}$
Undervoltage threshold for PGOOD	All			87.5		%$V_{O, set}$

Characteristic Curves

The following figures provide typical characteristics for the JRCS011 at 24V$_o$ and 25°C.

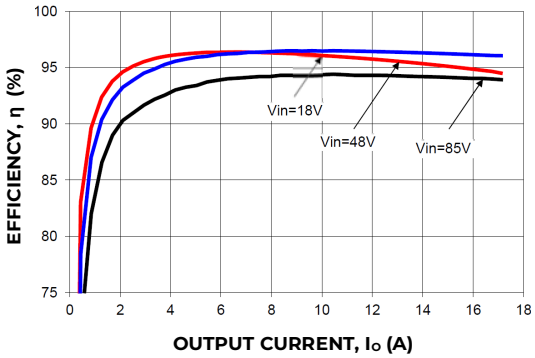


Figure 1. Converter Efficiency versus Output Current for V_{out} = 24V.

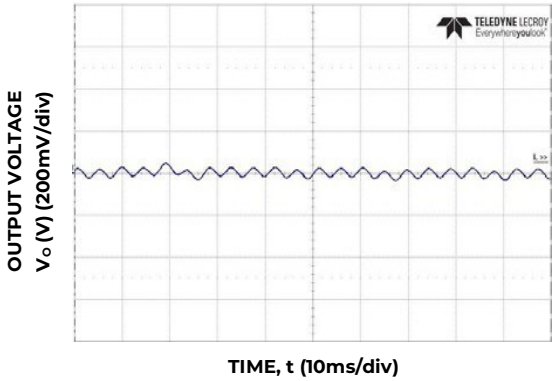


Figure 2. Typical output ripple and noise for V_{out} = 24V. Input voltage = 48V, C_{out}= 330 µF electrolytic + 15 x 2.2 µF ceramic.

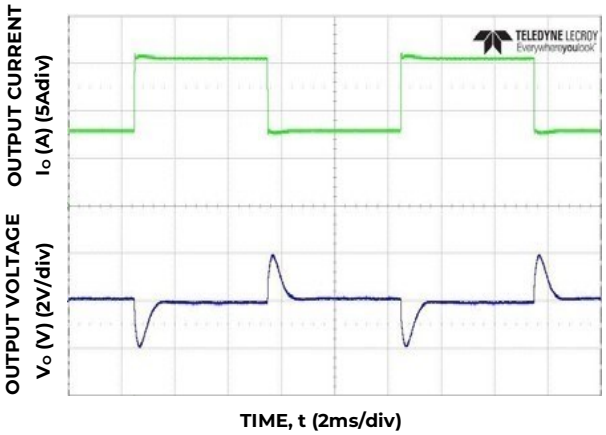


Figure 3. Transient Response to Dynamic Load Change from 50% to 100% at 48V$_{in}$, C_{OUT} = 330 µF electrolytic + 15 x 2.2 µF ceramic.

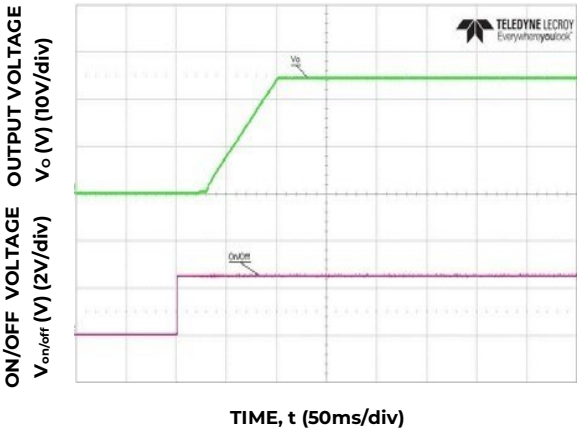


Figure 4. Typical Start-up Using On/Off Voltage (V_{IN}=48V, I_o = $I_{o,max}$).

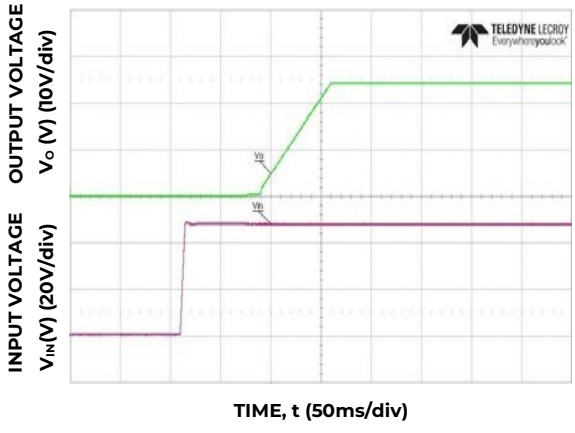


Figure 5. Typical Start-up Using Input Voltage (V_{IN} = 48V, I_o = $I_{o,max}$).

Characteristic Curves (continued)

The following figures provide typical characteristics for the JRCS011 at 48Vo and 25°C.

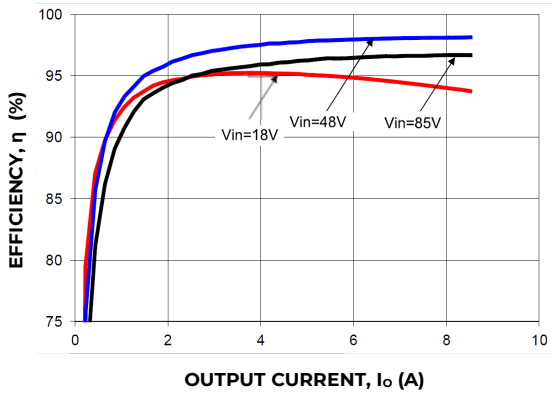


Figure 6. Converter Efficiency versus Output Current for V_{out} = 48v

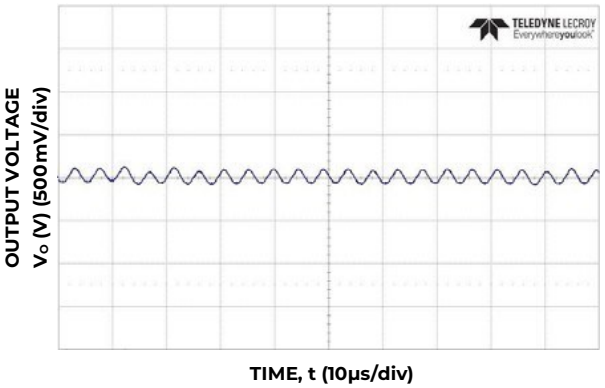


Figure 7. Typical output ripple and noise for V_{out} = 48V. Input voltage = 74V, C_{OUT} = 330 µF electrolytic + 15 x 2.2 µF ceramic.

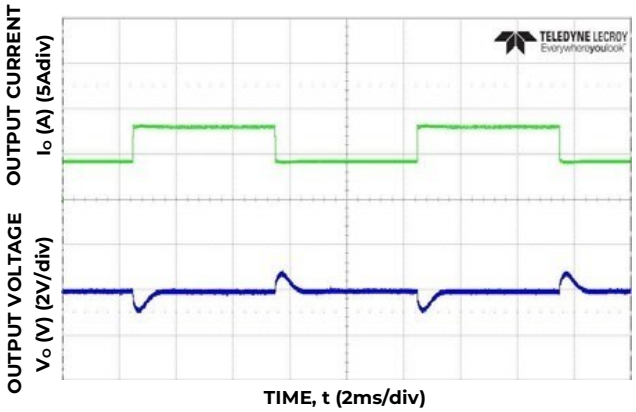


Figure 8. Transient Response to Dynamic Load Change from 50% to 100% at 74V_{in}, C_{OUT} = 330 µF electrolytic + 15 x 2.2 µF ceramic.

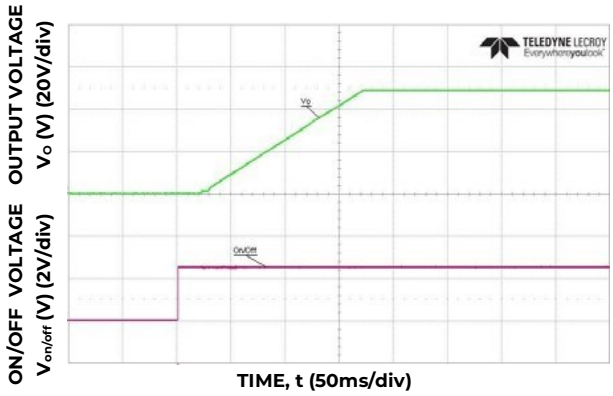


Figure 9. Typical Start-up Using On/Off Voltage (V_{IN}=74V, I_o = $I_{o,max}$).

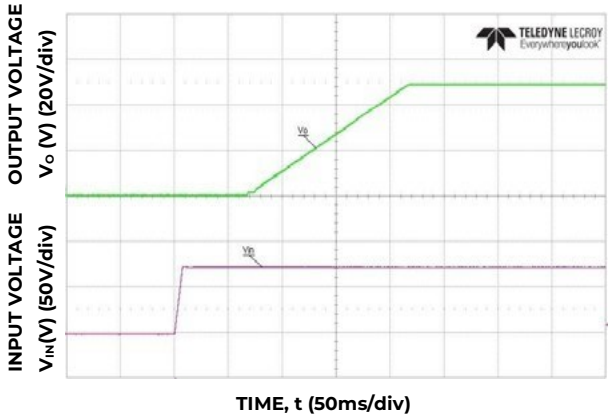


Figure 10. Typical Start-up Using Input Voltage (V_{IN} = 74V, I_o = $I_{o,max}$).

Characteristic Curves (continued)

The following figures provide typical characteristics for the JRCS011 at 60V$_o$ and 25°C.

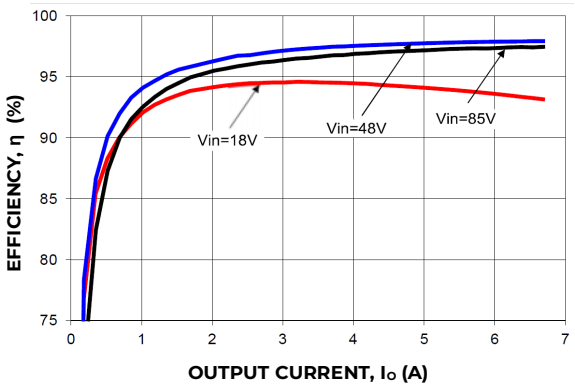


Figure 11. Converter Efficiency versus Output Current for V_{out}= 60V.

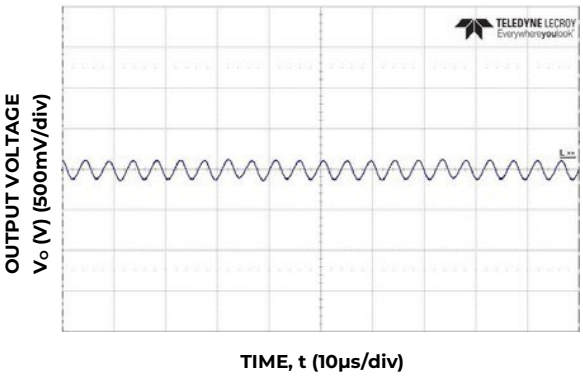


Figure 12. Typical output ripple and noise for V_{out} = 60V. Input voltage = 48V, C_{OUT} = 330 µF electrolytic+ 15 x 2.2 µF ceramic.

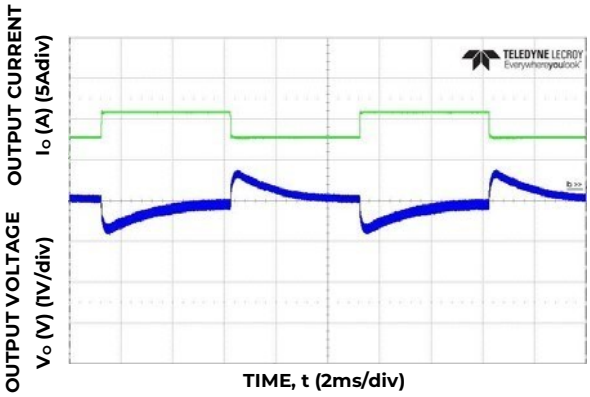


Figure 13. Transient Response to Dynamic Load Change from 50% to 100% at 48V$_{in}$, C_{out}= 330 µF electrolytic + 15 x 2.2 µF ceramic.

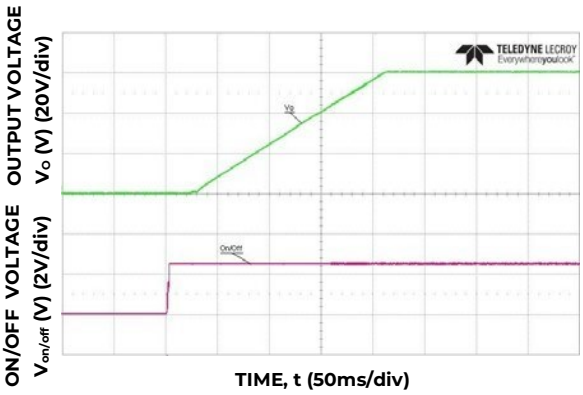


Figure 14. Typical Start-up Using On/Off Voltage (V_{IN}=48V, I_o =$I_{o,max}$).

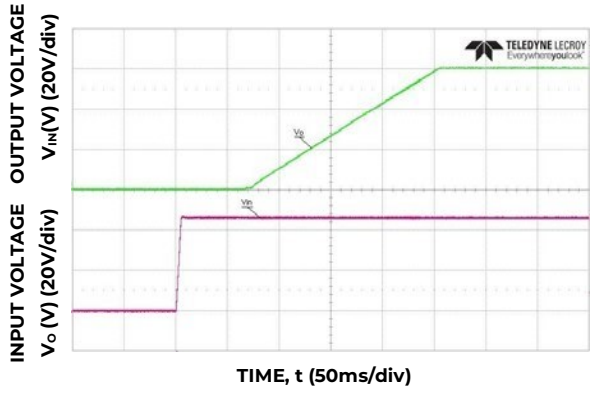


Figure 15. Typical Start-up Using Input Voltage (V_{IN} = 48V, I_o = $I_{o,max}$).

Characteristic Curves (continued)

The following figures provide typical thermal derating for the JRCS011 at various input and output voltages.

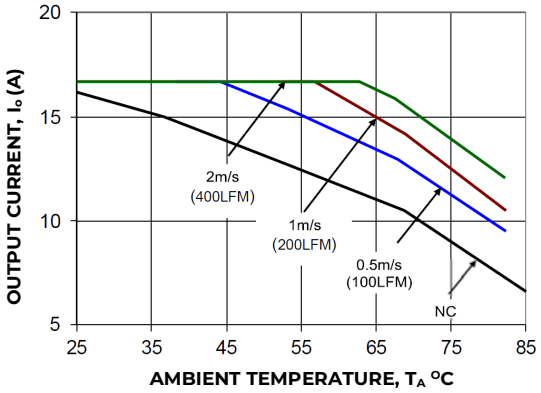


Figure 16. Derating Output Current versus Ambient Temperature and Air flow for V_{in}=48V, V_{out}=24V

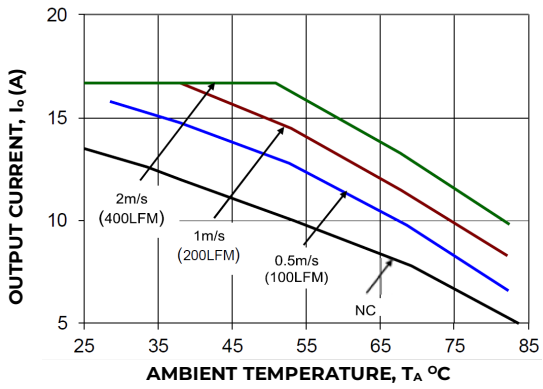


Figure 17. Derating Output Current versus Ambient Temperature and Air flow for V_{in}=74V, V_{out}=24V

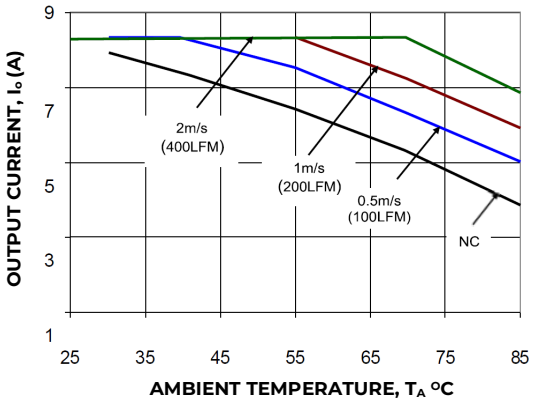


Figure 18. Derating Output Current versus Ambient Temperature and Air flow for V_{in}=24V, V_{out}=48V

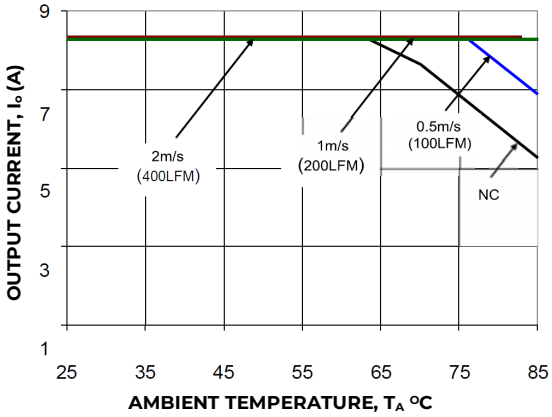


Figure 19. Derating Output Current versus Ambient Temperature and Airf low for V_{in}=74V, V_{out}=48V

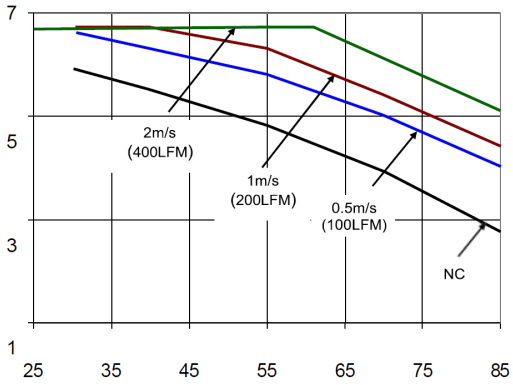


Figure 20. Derating Output Current versus Ambient Temperature and Air flow for V_{in}=24V, V_{out}=60V

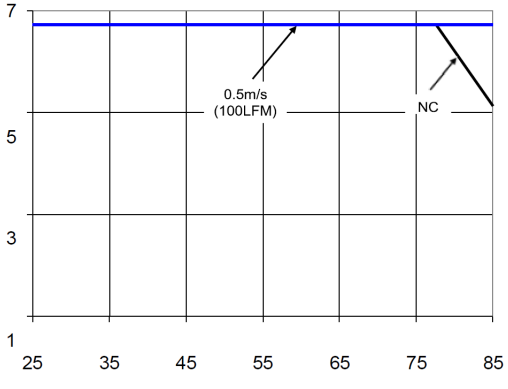


Figure 21. Derating Output Current versus Ambient Temperature and Air flow for V_{in}=48V, V_{out}=60V

Characteristic Curves (continued)

The following figures provide typical thermal derating for the JRCS011 at various input and output voltages.

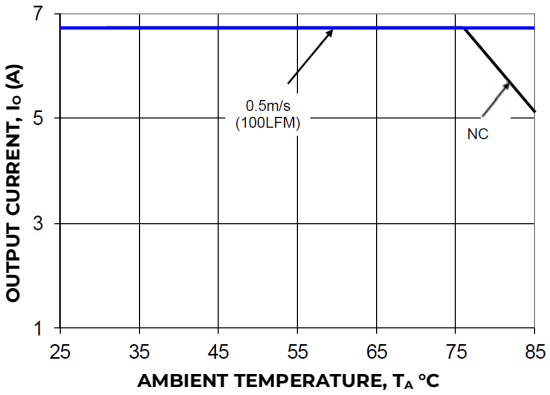


Figure 22. Derating Output Current versus Ambient Temperature and Air flow for V_{in}=74V, V_{out}=60V

Test Configurations

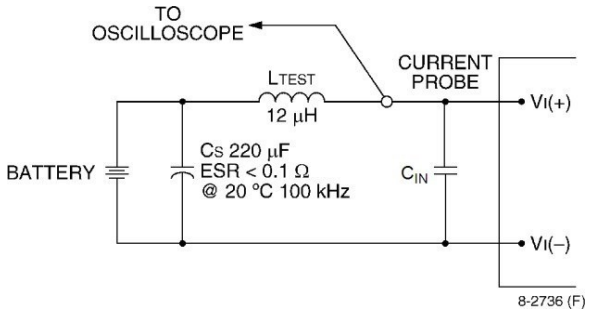


Figure 23. Input Reflected Ripple Current Test Setup.

NOTE: Measure input reflected ripple current with a simulated source inductance (L_{TEST}) of 1µH. Capacitor C_S offsets possible battery impedance. Measure current as shown above.

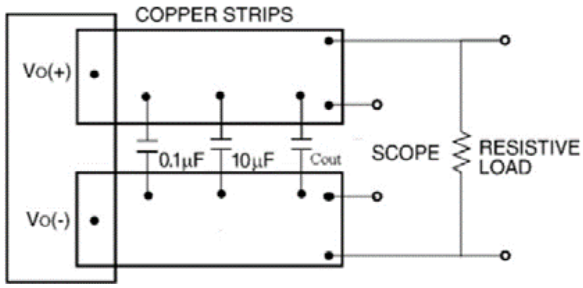


Figure 24. Output Ripple and Noise Test Setup.

Note: Use a C_{out} (470 µF Low ESR aluminum or tantalum capacitor typical), a 0.1 µF ceramic capacitor and a 10 µF ceramic capacitor, and Scope measurement should be made using a BNC socket. Position the load between 51 mm and 76 mm (2 in. and 3 in.) from the module.

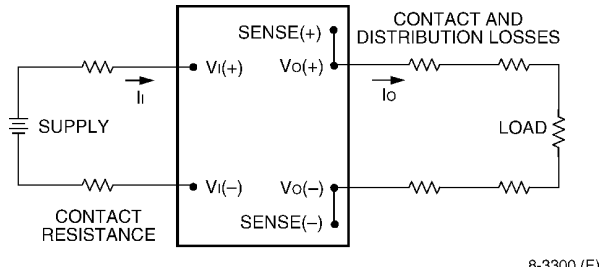


Figure 25. Output Voltage and Efficiency Test Setup.

Note: All measurements are taken at the module terminals. When socketing, place Kelvin connections at module terminals to avoid measurement errors due to socket contact resistance.

$$\eta = \left(\frac{[V_o(+) - V_o(-)]I_o}{[V_I(+) - V_I(-)]I_I} \right) \times 100\%$$

Design Considerations

Input Filtering

The JRCS016 module should be connected to a low ac-impedance source. A highly inductive source can affect the stability of the module. An input capacitance must be placed directly adjacent to the input pin of the module, to minimize input ripple voltage and ensure module stability. To minimize input voltage ripple, ceramic capacitors or low-ESR electrolytic capacitors are recommended at the input of the module.

Output Filtering

These modules are designed for low output ripple voltage and will meet the maximum output ripple specification with 3 x 10µF ceramic capacitors in parallel with a 330µF capacitor at the output of the module. However, additional output filtering may be required by the system designer for a number of reasons. First, there may be a need to further reduce the output ripple and noise of the module. Second, the dynamic response characteristics may need to be customized to a particular load step change.

To reduce the output ripple and improve the dynamic response to a step load change, additional capacitance at the output can be used. Low ESR electrolytic and ceramic capacitors are recommended to improve the dynamic response of the module. For stable operation of the module, limit the capacitance to less than the maximum output capacitance as specified in the electrical specification table.

Safety Considerations

For safety agency approval the power module must be installed in compliance with the spacing and separation requirements of the end-use safety agency standards, i.e.,

UL ANSI/UL* 62368-1 and CAN/CSA+ C22.2 No. 62368-1 Recognized, DIN VDE 0868-1/A11:2017 (EN62368- 1:2014/ A11:2017)

For the converter output to be considered meeting the requirements of safety extra-low voltage (SELV) or ES1, the input must meet SELV/ES1 requirements. The power module has extra-low voltage (ELV) outputs when all inputs are ELV.

The input to these units is to be provided with a slow-blow fuse with a maximum rating of TBD A in the positive input lead.

Feature Descriptions

Remote On/Off

The JRCS016 power modules feature an On/Off pin for remote On/Off operation with positive logic. Positive Logic On/Off signal turns the module ON during a logic High on the On/Off pin and turns the module OFF during a logic Low.

Overcurrent Protection

To provide protection in a fault (output overload) condition, the unit is 17*24equipped with internal current-limiting circuitry and can endure current limiting continuously. At the point of current-limit inception, the unit enters hiccup mode. The unit operates normally once the output current is brought back into its specified range. The current limit threshold is variable ranging from 16.7 A at 18.5V to 24V out to 6.67A at 60V_{out}.

Input Undervoltage Lockout

At input voltages below the input undervoltage lockout limit, module operation is disabled. The module begins to operate at an input voltage above the undervoltage lockout turn-on threshold.

Overtemperature Protection

To provide over temperature protection in a fault condition, the unit shuts down if the thermal reference point T_{ref}, exceeds 120°C. The module automatically restarts after it cools down.

Analog Output Voltage Programming

The output voltage of the JRCS016 can be set over the 18.5V to 60V range by connecting a resistor R_{Trim} between the TRIM and V_O(-) pins as shown in Fig. 26. The output voltage will be set according to the following equation relating it to the value of R_{Trim}:

$$R_{trim} = \left[\frac{700 - (10 \times V_o)}{(V_o - 4)} \right] k\Omega$$

If no external trim resistor is connected, the output voltage will be set at 18.5. Table 1 provides R_{trim} values required for some common output voltages.

Remote Sense

The JRCS016 modules have a Remote Sense feature to minimize the effects of distribution losses by regulating the voltage at the Remote Sense pins. The voltage between the V_O(+) and +SEN pins should not exceed 1V.

$V_{O, set}$ (V)	R_{trim} (KΩ)
18.5	35.51
20	31.25
24	23.0
28	17.5
32	13.571
36	10.625
48	5.0
52	3.75
54	3.2
60	1.786

Table 1

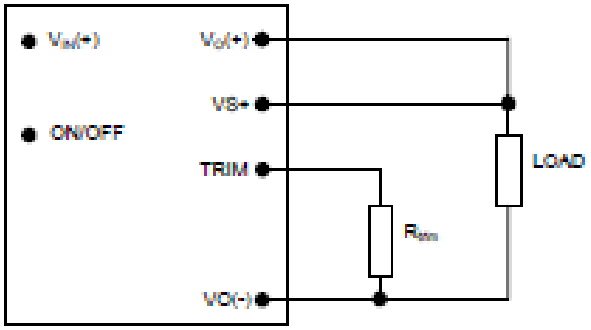


Figure 26. Circuit configuration for programming output voltage using an external resistor.

Load Sharing

For higher power requirements, the JRCS016-P module offers an optional feature for parallel operation (-P Option code). This feature provides a precise forced output voltage load regulation droop characteristic. The output set point and droop slope are factory calibrated to ensure optimum matching of multiple modules' load regulation characteristics. To implement load sharing, the following requirements should be followed:

- The V_{OUT}(+) and V_{OUT}(-) pins of all parallel modules must be connected together. Balance the trace resistance for each module's path to the output power planes, to ensure best load sharing and operating temperature balance.
- It is permissible to use a common Remote On/Off signal to start all modules in parallel.
- During system startup with over one module, the load cannot beyond 100% load of single module due to load unbalance during startup process.
- If fault tolerance is desired in parallel applications, output ORing devices should be used to prevent a single module failure from collapsing the load bus.

Feature Descriptions (continued)

Power Good

The JRCS016 modules have a Power Good (PGOOD) signal that is implemented with an open-drain output to indicate that the output voltage is within the regulation limits of the power module. The PGOOD signal will be de-asserted to a low state if any condition such as overtemperature, overcurrent or loss of regulation occurs that would result in the output voltage going ±10% outside the setpoint value. The PGOOD terminal can be connected through a pullup resistor (suggested value 100K) to a source of TBD VDC or lower.

For power supplies operating in parallel with their outputs not isolated from each other (e.g., with OR'ing FETs), the PGOOD signal indicates that the common output bus has the expected output voltage and does not provide an indication on any one particular power supply.

Digital Feature Descriptions

PMBus Interface Capability

The JRCS016 power modules have a PMBus interface that supports both communication and control. The PMBus Power Management Protocol Specification can be obtained from www.pmbus.org. The modules support a subset of version 1.1 of the specification (see Table 6 for a list of the specific commands supported). Most module parameters can be programmed using PMBus and stored as defaults for later use.

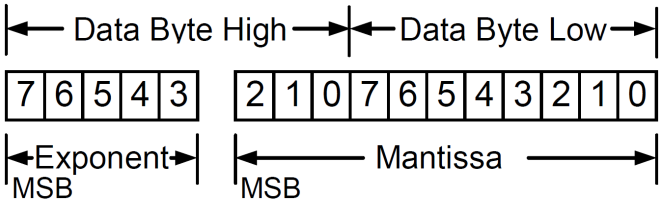
All communication over the module PMBus interface must support the Packet Error Checking (PEC) scheme. The PMBus master must generate the correct PEC byte for all transactions and check the PEC byte returned by the module.

The module has non-volatile memory that is used to store configuration settings. Not all settings programmed into the device are automatically saved into this non-volatile memory, only those specifically identified as capable of being stored can be saved (see Table 6 for which command parameters can be saved to non-volatile storage).

When one of the paralleled units is powered down, PMBus communication will stop or abnormal.

PMBus Data Format

For commands that set thresholds, voltages or report such quantities, the module supports the "Linear" data format among the three data formats supported by PMBus. The Linear Data Format is a two byte value with an 11-bit, two's complement mantissa and a 5-bit, two's complement exponent. The format of the two data bytes is shown below:



The value is of the number is then given by

$$\text{Value} = \text{Mantissa} \times 2^{\text{Exponent}}$$

PMBus Addressing

The power module can be addressed through the PMBus using a device address. The module has 64 possible addresses (0 to 63 in decimal) which can be set using resistors connected from the ADDR0 and ADDR1 pins to GND. Note that some of these addresses (0 through 12, 40, 44, 45, and 55 in decimal) are reserved according to the SMBus specifications and may not be useable. The address is set in the form of two octal (0 to 7) digits, with each pin setting one digit. The ADDR1 pin sets the high order digit and ADDR0 sets the low order digit. The resistor values suggested for each digit are shown in Table 2 (1% tolerance resistors are recommended).

Digit	Resistor Value (KΩ)
0	10
1	15.4
2	23.7
3	36.5
4	54.9
5	84.5
6	130
7	200

Table 2

Digital Feature Descriptions (continued)

PMBus Addressing (continued)

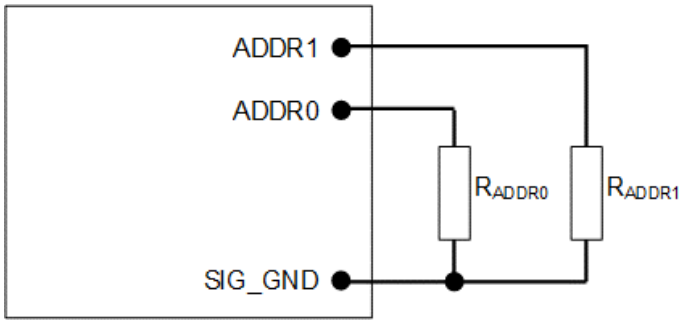


Figure 27. Circuit showing connection of resistors used to set the PMBus address of the module.

The user must know which I^2C addresses are reserved in a system for special functions and set the address of the module to avoid interfering with other system operations. Both 100kHz and 400kHz bus speeds are supported by the module. Connection for the PMBus interface should follow the High-Power DC specifications given in section 3.1.3 in the SMBus specification V2.0 for the 400kHz bus speed or the Low Power DC specifications in section 3.1.2. The complete SMBus specification is available from the SMBus web site, www.pmbus.org.

PMBus Commands

Hex Code	Command	Brief Description								Non-Volatile Memory Storage
03	CLEAR_FAULTS	Clear any fault bits that may have been set, also releases the SMBALERT# signal ifthe device has been asserting it.								
11	STORE_DEFAULT_ALL	Copies all current register settings in the module into non-volatile memory(EEPROM) on the module. Takes about 50ms for the command to execute.								
12	RESTORE_DEFAULT_ALL	Restores all current register settings in the module from values in the module non-volatile memory (EEPROM)								
20	VOUT_MODE	The module has MODE set to Linear and Exponent set to -8. These values cannot bechanged								
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Mode			Exponent				
		Default Value	0	0	0	1	1	0	0	0
28	VOUT_DROOP	Range limits (max/min): 50.0/0 Units: 16mv/A DEFAULT VALUE: 5.0 (with –P)								
35	VIN_ON	Sets the value of input voltage at which the module turns on								YES
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Exponent					Mantissa		
		Default Value	1	1	1	0	1	0	0	0
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	1	0	0	0	1	0	0	0
36	VIN_OFF	Sets the value of input voltage at which the module turns off								YES
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Exponent					Mantissa		
		Default Value	1	1	1	0	1	0	0	0
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	0	1	1	1	1	0	0	0
55	VIN_OV_FAULT_LIMIT	Sets the voltage level for an input overvoltage fault.								YES
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Exponent					Mantissa		
		Default Value	1	1	1	0	1	0	1	0
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	1	1	0	0	1	0	0	0

Table 6

PMBus Commands (continued)

Hex Code	Command	Brief Description								Non-Volatile Memory Storage
79	STATUS_WORD	Returns two bytes of information with a summary of the module's fault/warningconditions. This PMBus command does not support to report correct state (Such as OVP, OCP, OTP, Input UVP/OVP, ON/OFF), and no other command can be used to report thesefailures.								
		Format	Unsigned Binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Flag	X	X	X	X	X	X	X	X
		Default Value	0	0	0	0	0	0	0	0
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Flag	X	X	X	X	X	TEMP	CML	OTHER
		Default Value	0	0	0	0	0	0	0	0
7E	STATUS_CML	Returns one byte of information with the status of the module's communicationrelated faults								
		Format	Unsigned Binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Flag	Invalid Command	Invalid Data	PEC Fail	X	X	X	Other Comm Fault	X
		Default Value	0	0	0	0	0	0	0	0
88	READ_VIN	Returns the value of the input voltage applied to the module								
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Exponent					Mantissa		
		Default Value	1	1	1	0	1	0	0	0
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Mantissa							
		Default Value	0	0	0	0	0	0	0	0
8B	READ_VOUT	Returns the value of the output voltage of the module. Exponent is fixed at -8.								
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Mantissa							
		Default Value	0	0	0	0	0	0	0	0
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Mantissa							
		Default Value	0	0	0	0	0	0	0	0

Table 6 (continued)

PMBus Commands (continued)

dHex Code	Command	Brief Description								Non-Volatile Memory Storage
8C	READ_IOUT	Returns the value of the output current of the module								
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Exponent					Mantissa		
		Default Value	1	1	1	0	0	0	0	0
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Mantissa							
		Default Value	0	0	0	0	0	0	0	0
8D	READ_TEMP_1	Returns the value of the temperature sensor 1 of the module								
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Exponent					Mantissa		
		Default Value	1	1	1	1	0	0	0	0
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Mantissa							
		Default Value	0	0	0	0	0	0	0	0
8E	READ_TEMP_2	Returns the value of the temperature sensor 2 of the module								
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Exponent					Mantissa		
		Default Value	1	1	1	1	0	0	0	0
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Function	Mantissa							
		Default Value	0	0	0	0	0	0	0	0
98	PMBUS_REVISION	Returns one byte indicating the module is compliant to PMBus Spec. 1.1 (read only)								
		Format	Unsigned Binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r	r	r
		Default Value	0	0	0	1	0	0	0	1
D1	VOUT_CAL_GAIN	Applies a gain correction to the READ_VOUT command results to calibrate out gainerrors in module measurements of the output voltage								YES
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	Variable based on factory calibration							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	Variable based on factory calibration							

Table 6 (continued)

PMBus Commands (continued)

Hex Code	Command	Brief Description								Non-Volatile Memory Storage
D2	VOUT_CAL_OFFSET	Applies an offset to the READ_VOUT command results to calibrate out offset errorsin module measurements of the output voltage. Exponent is fixed at -8.								YES
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	Variable based on factory calibration							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	Variable based on factory calibration							
D3	VIN_CAL_GAIN	Returns the value of the gain correction term used to correct the measured inputvoltage.								YES
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	Variable based on factory calibration							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	Variable based on factory calibration							
D4	VIN_CAL_OFFSET	Returns the value of the offset correction term used to correct the measured inputvoltage.								YES
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r/w	r/w	r/w
		Function	Exponent					Mantissa		
		Default Value	1	1	1	0	1	V		
		Bit Position	7	6	5	4	3	2	1	0
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	V: Variable based on factory calibration							
D6	IOUT_CAL_GAIN	Returns the value of the gain correction term used to correct the measured outputcurrent								YES
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	Variable based on factory calibration							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	Variable based on factory calibration							
D7	IOUT_CAL_OFFSET	Returns the value of the offset correction term used to correct the measured outputcurrent								YES
		Format	Linear, two's complement binary							
		Bit Position	7	6	5	4	3	2	1	0
		Access	r	r	r	r	r	r/w	r/w	r/w
		Function	Exponent					Mantissa		
		Default Value	1	1	1	0	0	V		
		Bit Position	7	6	5	4	3	2	1	0
		Access	r/w	r/w	r/w	r/w	r/w	r/w	r/w	r/w
		Function	Mantissa							
		Default Value	V: Variable based on factory calibration							
DB	FW_REV	Returns the firmware version in format of "0xMj.Mn.Bh.Bl"								

Thermal Considerations

Power modules operate in a variety of thermal environments; however, sufficient cooling should always be provided to help ensure reliable operation.

Considerations include ambient temperature, airflow, module power dissipation, and the need for increased reliability. A reduction in the operating temperature of the module will result in an increase in reliability. The thermal data presented here is based on physical measurements taken in a wind tunnel. The test set-up is shown in Figure 28. The preferred airflow direction for the module is in Figure 29.

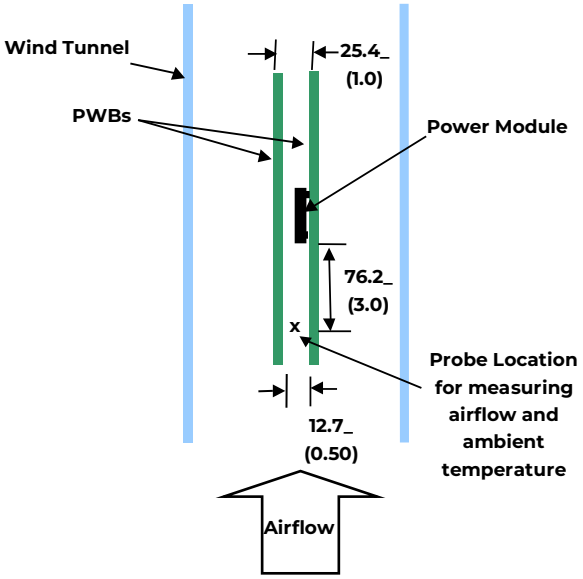


Figure 28. Thermal Test Set-up.

The thermal reference points, $T_{ref}1$ and $T_{ref}2$ used in the specifications are also shown in Figure 29. For reliable operation the temperatures at these points should not exceed 98°C. The output power of the module should not exceed the rated power of the module ($V_{o,set}$ x $I_{o,max}$).

Please refer to the Application Note "Thermal Characterization Process for Open-Frame Board-Mounted Power Modules" for a detailed discussion of thermal aspects including maximum device temperatures.

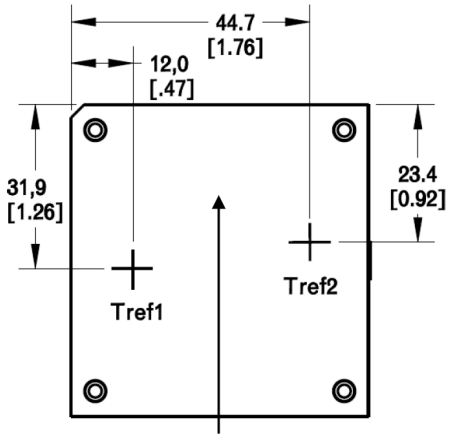


Figure 29. Location of hot-spots of the module ($T_{ref}1$ and $T_{ref}2$).

Layout Considerations

The JRCS016 power module series are constructed using a single PWB with integral base plate; as such, component clearance between the bottom of the power module and the mounting (Host) board is limited. Avoid placing copper areas on the outer layer directly underneath the power module.

Post Solder Cleaning and Drying Considerations

Post solder cleaning is usually the final circuit-board assembly process prior to electrical board testing. The result of inadequate cleaning and drying can affect both the reliability of a power module and the testability of the finished circuit-board assembly. For guidance on appropriate soldering, cleaning and drying procedures, refer to OmniOn Board Mounted Power Modules: Soldering and Cleaning Application Note.

Through-Hole Lead-Free Soldering Information

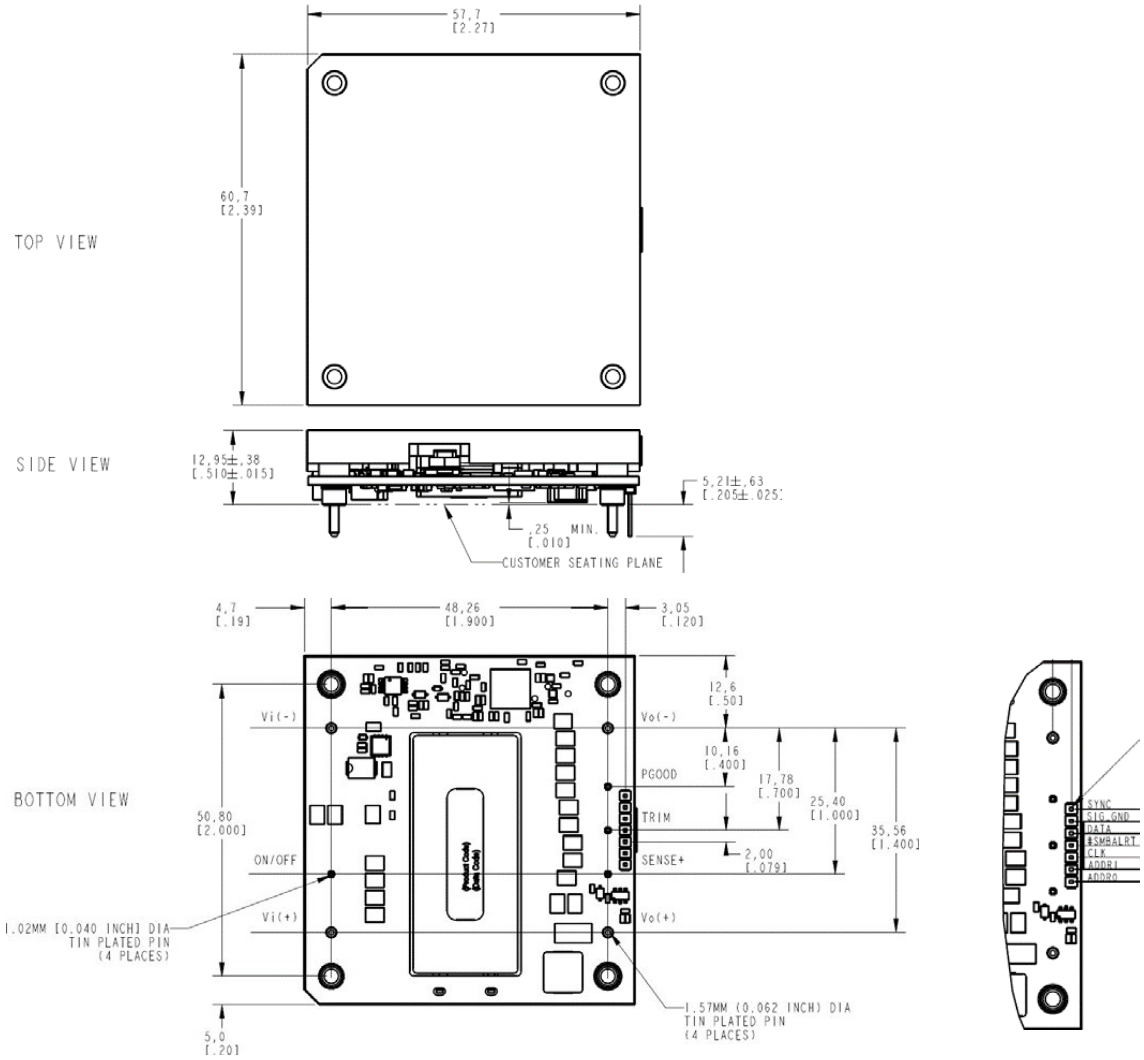
The RoHS-compliant through-hole products use the SAC (Sn/Ag/Cu) Pb-free solder and RoHS-compliant components. They are designed to be processed through single or dual wave soldering machines. The pins have an RoHS- compliant finish that is compatible with both Pb and Pb-free wave soldering processes. A maximum preheat rate of 3°C/s is suggested. The wave preheat process should be such that the temperature of the power module board is kept below 210°C. For Pb solder, the recommended pot temperature is 260°C, while the Pb-free solder pot is 270°C max. The JRCS016 cannot be processed with paste- through-hole Pb or Pb-free reflow process. If additional information is needed, please consult with your OmniOn representative for more details.

Mechanical Outline

Dimensions are in millimeters and (inches).

Tolerances: x.x mm ± 0.5 mm (x.xx in. ± 0.02 in.) [unless otherwise indicated]

x.xx mm ±0.25 mm (x.xxx in ± 0.010 in.)



PIN	FUNCTION	PIN	FUNCTION	PIN	FUNCTION
1	VI(+)	6	TRIM	11	DATA
2	ON/OFF	7	+SEN	12	#SMBALRT
3	VI(-)	8	V_O(+)	13	CLK
4	V_O(-)	9	SYNC	14	ADDR1
5	PGOOD	10	SIG_GND	15	ADDR0

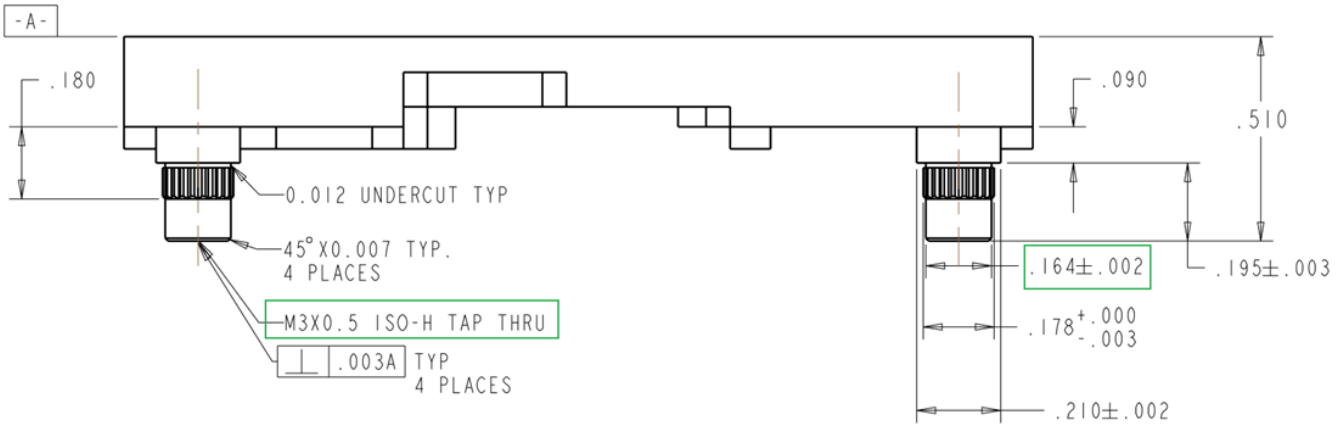
Note: Pins 9, 10, 11, 12, 13, 14 and 15 can be NC when modules do not have the PMBus function.

Mechanical Outline—Side View

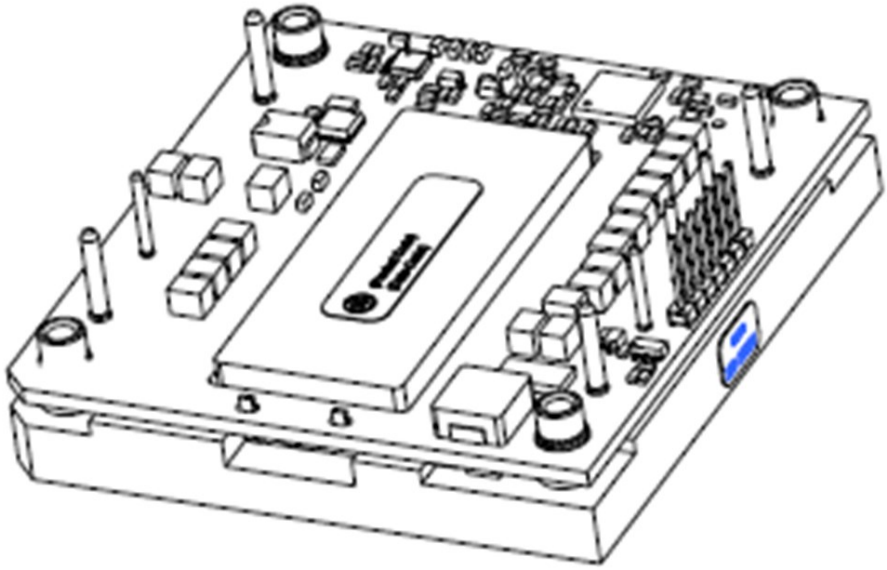
Dimensions are in millimeters and (inches).

Tolerances: x.x mm ± 0.5 mm (x.xx in. ± 0.02 in.) [unless otherwise indicated]

x.xx mm ±0.25 mm (x.xxx in ± 0.010 in.)



PIN SIDE VIEW



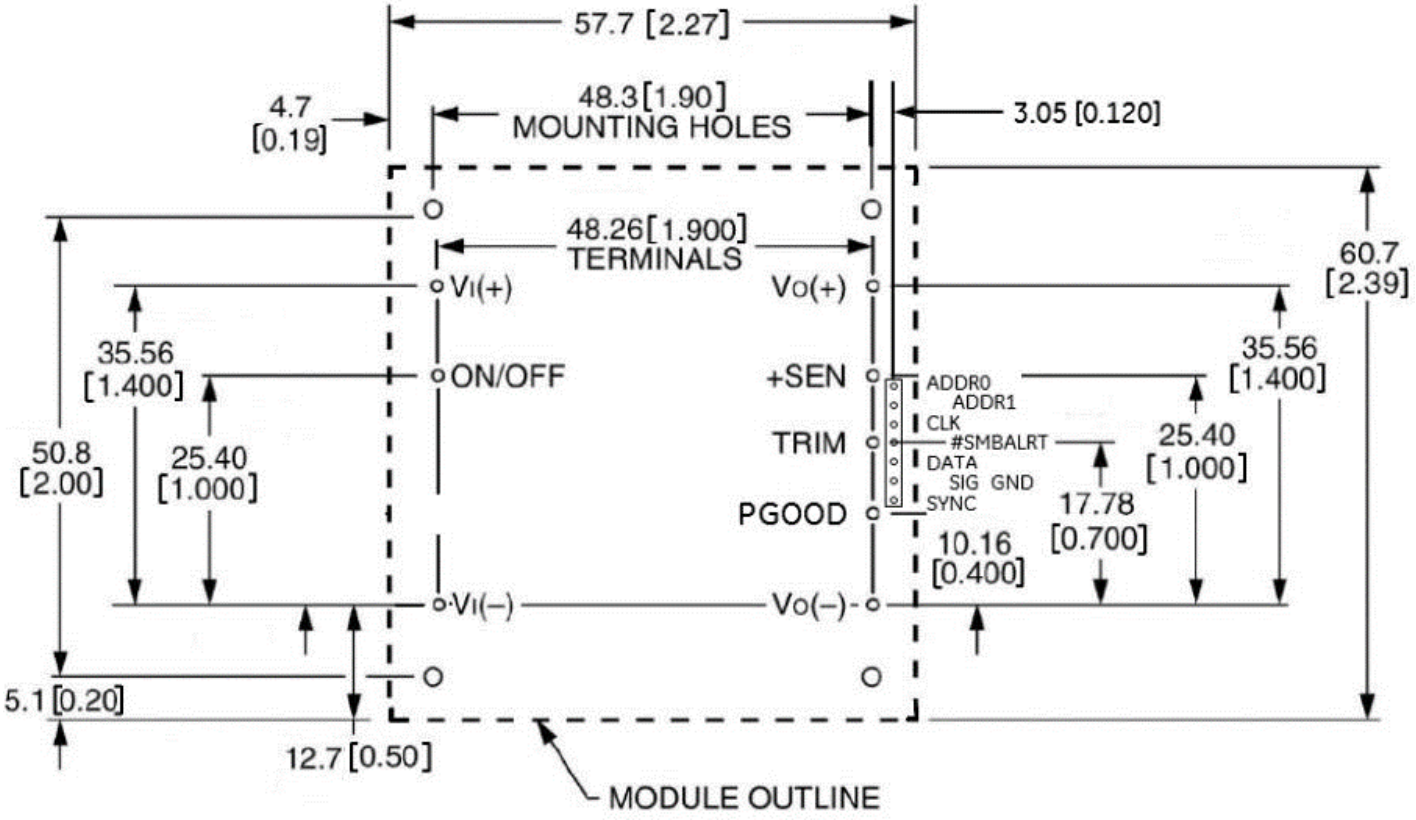
SCALE 2.000

Recommended Pad Layout for Through Hole Module

Dimensions are in millimeters and (inches).

Tolerances: x.x mm ± 0.5 mm (x.xx in. ± 0.02 in.) [unless otherwise indicated]

x.xx mm ±0.25 mm (x.xxx in ± 0.010 in.)



Product Matrix

Device Code	Input Voltage Range	Output Voltage	Output Current	On/Off Logic	Ordering code
JRCS016A0S4-HZ	18 – 85V_{dc}	18.5 - 60V_{dc}	16.7A to 6.7A	Positive	1600130338A
JRCS016A0S64-HZ	18 – 85V_{dc}	18.5 - 60V_{dc}	16.7A to 6.7A	Positive	150038175
JRCS016A0S4-PHZ	18 – 85V_{dc}	18.5 - 60V_{dc}	16.7A to 6.7A	Positive	1600311837A
JRCS016A0S64-PHZ	18 – 85V_{dc}	18.5 60V_{dc}	16.7A to 6.7A	Positive	1600321885A

Device Description

	Characteristic	Character and Position												Definition
Ratings	Form Factor	**J**												**J** = Half Brick
	Family Designator		**RC**											
	Input Voltage			**S**										**S** = Special Range, 18V-85V
	Output Power				**016A0**									**016A0** = 016.0 Amps Maximum Output Current
	Output Voltage					**S**								**S** = Special Voltage, 18.5-60V
Options	Pin Length						**6** **8**							**Omit** = Default Pin Length shown in Mechanical Outline Figures **6** = Pin Length: 3.68 mm ± 0.25mm , (0.145 in. ± 0.010 in.) **8** = Pin Length: 2.79 mm ± 0.25mm , (0.110 in. ± 0.010 in.)
	Action following Protective Shutdown							**4**						**Omit** = Latching Mode **4** = Auto-restart following shutdown (Overcurrent/ Overvoltage)
	On/ Off Logic								**1**					**Omit** = Positive Logic **1** = Negative Logic
		—												
	Customer Specific									**XY**				**XY**= Customer Specific Modified Code, Omit for Standard Code
	Optional Features										**P** **H**			**Omit** = Standard open Frame Module **P** = Paralleling with current sharing between outputs **H** = Heat plate, for use with heat sinks or cold-walls
	RoHS												**Z**	**Omit** = RoHS 5/ 6, Lead Based Solder Used **Z** = RoHS Compliant

-Z refers to RoHS compliant parts

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Change History (excludes grammar & clarifications)

Revision	Date	Description of the change
1.7	09-20-2022	Added Pin Side View
1.8	11-22-2023	Updated as per OmniOn template

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